

The condensed water coming out of the condenser passes through expansion valve followed by the evaporator where the cooling effect is produced. The low pressure vapor is then absorbed by the absorbent in the absorber producing weak solution. The conventional VAR system with capacity of 10TR is considered. Total entropy generation in the system can be obtained by summing up entropy generated in all components.

$$\dot{S}_{\text{Total}} = \sum_{j=1}^N \dot{S}_{\text{total}} = \dot{S}_{\text{collector}} + \dot{S}_G + \dot{S}_C + \dot{S}_A + \dot{S}_E + \dot{S}_{\text{RHE}} + \dot{S}_{\text{SHE}} + \dot{S}_{\text{rev}}$$

III. ARTIFICIAL NEURAL NETWORKS (ANN)

ANN is originally developed to simulate the function of the human brain or neural system, resulting in systems that learn by experience. The use of ANNs has increased dramatically in recent years in the field of applied mechanics, logistics, manufacturing and etc. in order to model complex system behavior, the human brain consist of large number (approx. 1011) of highly connected neurons those have many desirable characteristics not present in modern sequential computers. Some of these characteristics are:

- 1) Massive parallelism
- 2) Distributed representation and computation
- 3) Learning ability
- 4) Generalization ability.

ANN involves processing elements or neurons and interconnection weights between neurons. These interconnection weight determine the nature and the strength of the connection between neurons. In ANN information processing occurs at many neurons and signals are passed between neurons over interconnection links.

Each interconnection link has its associated weight that multiplies the signals transmitted and each neurons applied and activation function to determine its output signal. A single neuron with R element input vector shown in fig.

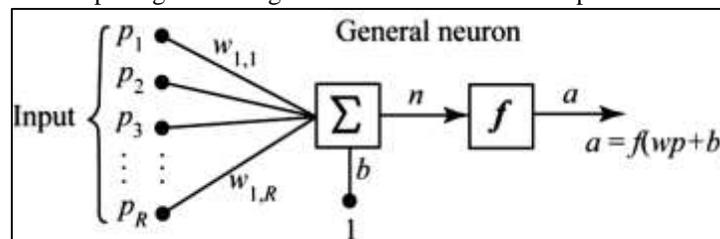


Fig. 2: ANN structure

IV. PREDICTION OF COEFFICIENT OF PERFORMANCE

An absorption system consists of the evaporator, generator, condenser, absorber, solution pump, solution heat exchanger and expansion valve. A schematic representation of the absorption cycle is given in Fig. 3. The energy and mass balance equations of the various components of an absorption system are given in Table 1.

The cooling coefficient of performance (COP) of the absorption system is defined as the heat load in the evaporator per unit of heat load in the generator and can be written as:

$$\text{COP} = \frac{Q_E}{Q_G}$$

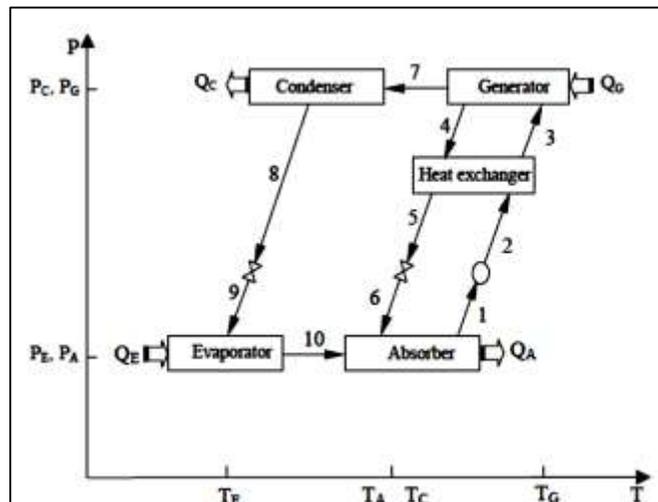


Fig. 3: Schematic representation of the absorption system

Table - 1
The energy and mass balance equations of absorption system components

System components	mass balance equations	Energy balance equations
Pump	$m1 = m2; x1 = x2$	$W = m2h2 - m1h1$
Solution heat exchanger	$m2 = m3, m4 = m5; x2 = x3, x4 = x5$	$m2h2 + m4h4 = m3h3 + m5h5$
Solution expansion valve	$m5 = m6; x5 = x6$	$h5 = h6$
Absorber	$m1 = m6 + m10; m1x1 = m6x6 + m10x10$	$QA = m6h6 + m10h10 - m1h1$
Generator	$m3 = m4 + m7; m3x3 = m4x4 + m7x7$	$QG = m4h4 + m7h7 - m3h3$
Condenser	$m7 = m8; x7 = x8$	$QK = m7h7 - m8h8$
Refrigerant expansion valve	$m8 = m9; x8 = x9$	$h8 = h9$
Evaporator	$m9 = m10; x9 = x10$	$QE = m10h10 - m9h9$

V. MODELING OF THE THERMODYNAMIC PROPERTIES WITH ANN

Determination of the thermodynamic properties of fluid pairs used in the absorption systems is one of the most difficult problems. Complex empirical expressions for entropy of Li Br–water solution in the temperature range of 0–190 8C and salt concentration of 0–75%. In order to develop a formulation procedure for entropy of Li Br–water solutions using ANNs, these data were used. The inputs of the network are temperature and concentration and the output is entropy of the fluid pairs.

In this study, the back-propagation learning algorithm is used in a feed-forward, single hidden layer network. Logistic sigmoid transfer function is used as the activation function for both the hidden layer and the output layer. The transfer function used is presented in Equation. The values of the training and test data were normalized to a range of 0–1. Levenberg–Marquardt (LM) Back-Propagation training was repeatedly applied until satisfactory training is achieved.

$$F(z) = \frac{1}{1 + e^{-z}}$$

Where z is the weighted sum of the input. The computer program was performed under MATLAB environment using the neural network toolbox. The data set for the entropy of Li Br–water solution available included 100% data patterns. From these 70% data patterns were used for the training of the network and the remaining 30% patterns were randomly selected and used as test data set.

Fig. 4 shows the architecture of the ANN used for LiBr–water solution entropy prediction. In this, the temperature and concentration are the input data and Entropy of the solution is the actual output. The configuration 2-8-1 appeared to be the most optimal topology for this application.

VI. PROPOSED WORK

A. Artificial Neural Networks

Although the concept of artificial neural network (ANN) analysis was discovered nearly 50 years ago, it is only in the last two decades that application software has been developed to handle practical problems. ANNs are good for some tasks while lacking in some others. Specifically, they are good for tasks involving incomplete data sets, fuzzy or incomplete information and for highly complex and ill-defined problems, where humans usually make decisions on an intuitional basis.

ANNs have been applied successfully in various fields of mathematics, engineering, medicine, economics, meteorology, psychology, neurology and many others. They have also been used in weather and market trends forecasting, in the prediction of mineral exploration sites, in electrical and thermal load prediction, in adaptive and robotic control and many others.

Artificial neural networks are systems of weight vectors, whose component values are established through various machine learning algorithms, which take as input a linear set of pattern inputs and produce as output a numerical pattern representing the actual output. ANNs mimic somewhat the learning process of a human brain. Instead of complex rules and mathematical routines, ANNs are able to learn key information patterns within a multi-information domain. In addition, inherently noisy data do not seem to present a problem, as ANNs are tolerant to noise variations.

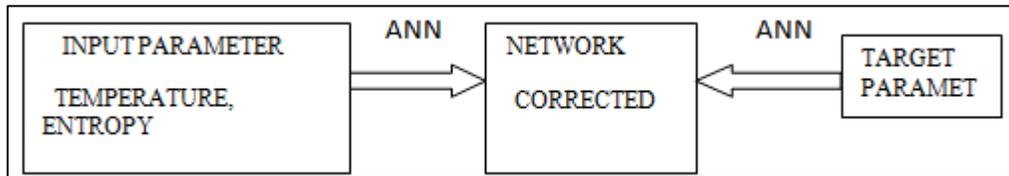
Artificial neural networks differ from the traditional modeling approaches in that they are trained to learn solutions rather than being programmed to model a specific problem in the normal way. They are usually used to address problems that are intractable or cumbersome to solve with traditional methods. They can learn from examples, are fault tolerant in the sense that they are able to handle noisy and incomplete data are able to deal with non-linear problems and, once trained, can perform predictions at very high speed. ANNs have been used in many engineering applications such as in control systems, in classification and in modeling complex process transformations.

Neural networks are composed of simple elements operating in parallel. These elements are inspired by biological nervous systems. As in nature, the network function is determined largely by the connections between elements. A neural network can be trained to perform a particular function by adjusting the values of the connections (weights) between the elements. Commonly, neural networks are adjusted, or trained, so that a particular input leads to a specific target output. Such a situation is shown in Fig Here, the network is adjusted, based on a comparison of the output and the target, until the network output matches the target. Typically, many such input/target output pairs are used to train a network. Batch training of a network proceeds by

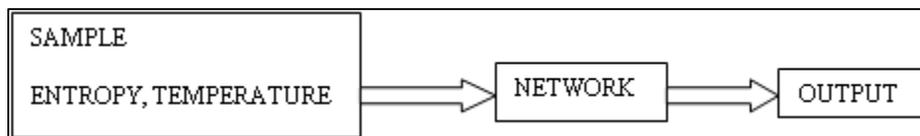
making weight and bias changes based on an entire set (batch) of input vectors. Incremental training changes the weights and biases of a network as needed after presentation of each individual input vector. Incremental training is sometimes referred to as “on line” or “adaptive” training.

There are different learning algorithms that can be applied to train a neural network. The most popular of them is the back propagation algorithm, which has different variants. Standard back propagation is a gradient descent algorithm. It is very difficult to know which training algorithm will be the fastest for a given problem, and the best one is usually chosen by trial and error. An ANN with a back propagation algorithm learns by changing the connection weights, and these changes are stored as knowledge

B. Train



C. Testing



D. Network Configuration

NETWORK TYPE	FEED FORWARD BACK PROPAGATION NETWORK
ADAPTIVE FUNCTION	LEARN GDM
NETWORK LAYERS	THREE
TRANSFER FUNCTION	LOGSING
EPOCHS	1000
MINIMUM GRADIANT	$1e^{-5}$
MAXIMUM_FAIL	1000
I_r	0.01
I_r_{ince}	1.05
I_r_{dec}	0.7
Max_pref_inc	1.04
Maximum change	0.9

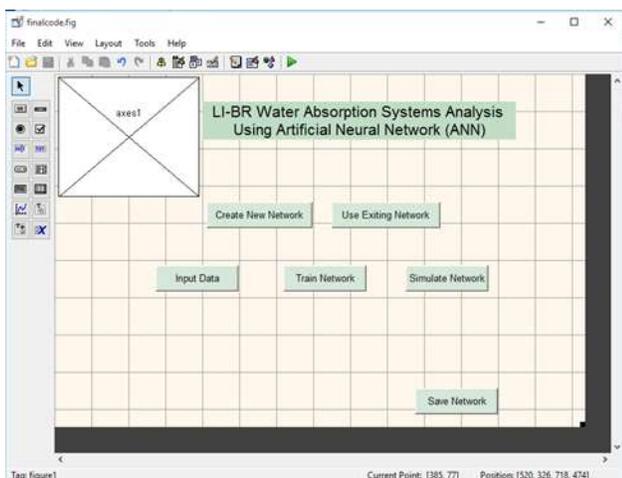


Fig. 4: Main GUI Building

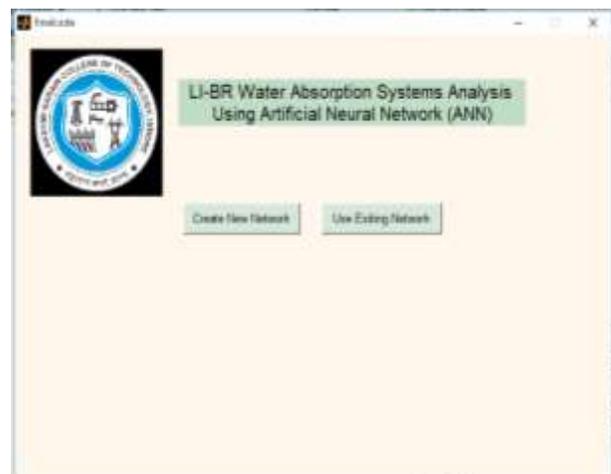


Fig. 5: Running GUI Code



Fig. 6: Create New Network



Fig. 7: Input data and target to network

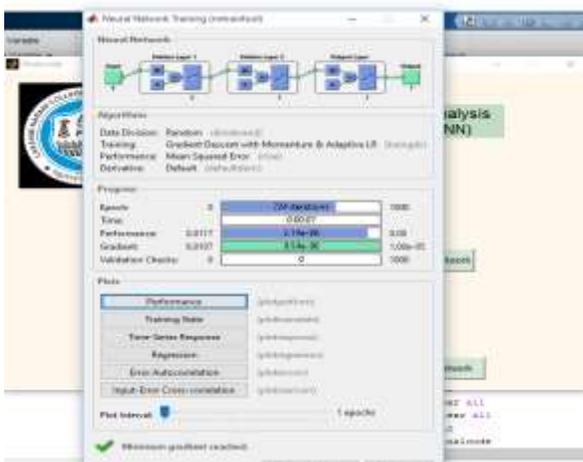


Fig. 8: Training Network

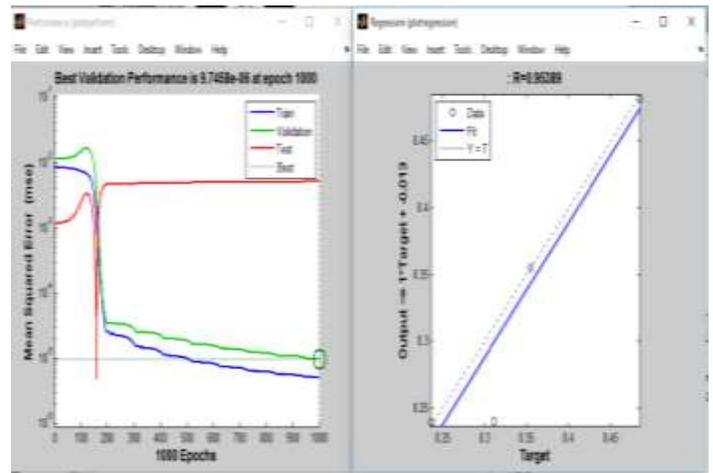


Fig. 9: Performance and Regressions Plot



Fig. 10: Testing Network by giving Sample Data

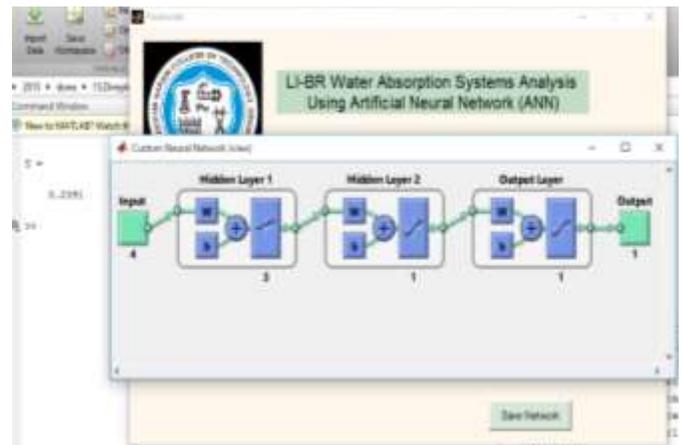


Fig. 11: Result of Test data

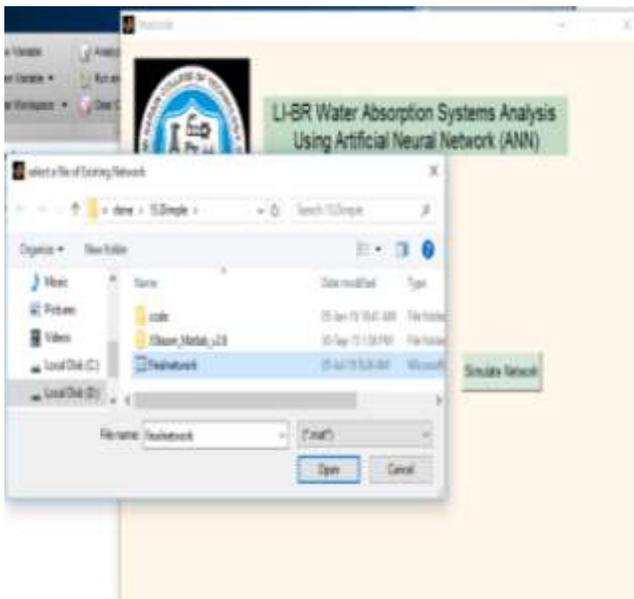


Fig. 12: Use Existing Network

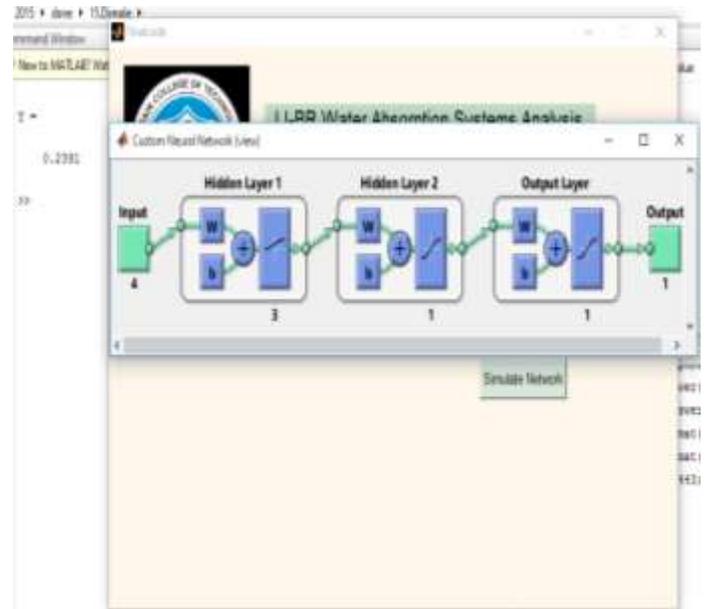
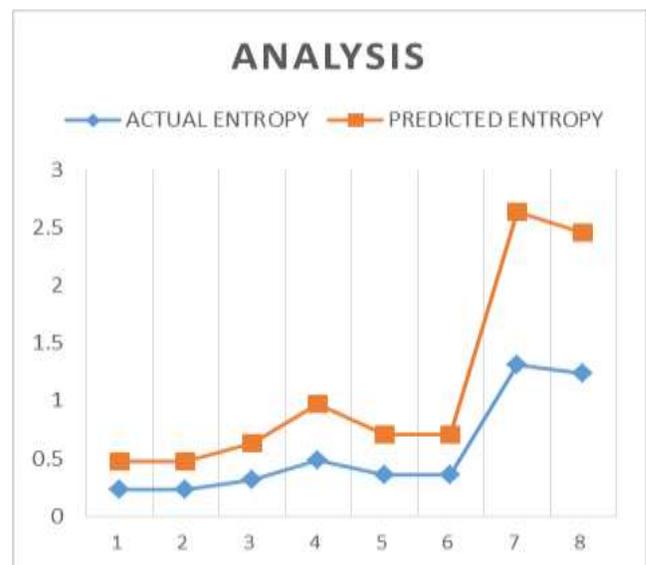
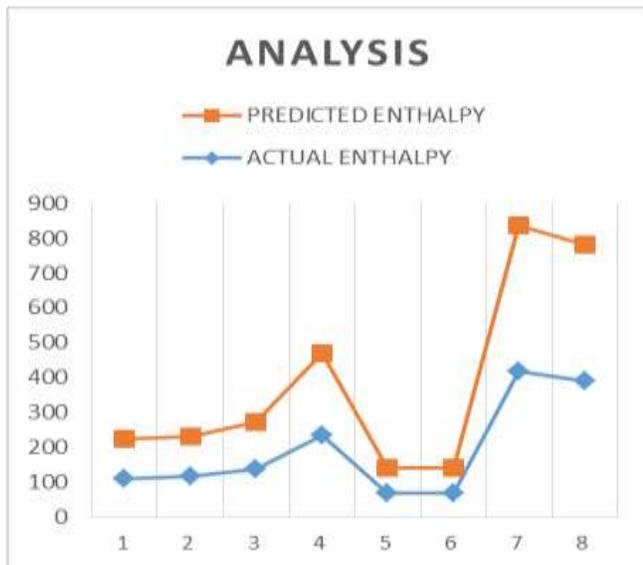


Fig. 13: Simulate Network

NO.	INPUT PARAMETER			OUTPUT PARAMETER			
	TEMPERATURE	CONCENTRATION	MASS	ACTUAL ENTHALPY	ACTUAL ENTROPY	PREDICTED ENTHALPY	PREDICTED ENTROPY
1	40	58.7	0.0443	112.94	0.236	112.23	0.24
2	40	58.7	0.0443	117.31	0.236	116.21	0.24
3	52.5	58.7	0.0443	137.72	0.3113	137	0.32
4	90	63.46	0.0401	235.84	0.4846	233.24	0.484
5	65	63.46	0.0401	70.55	0.3548	70.44	0.354
6	65	63.46	0.0401	70.55	0.3548	70.43	0.354
7	90	0	0.85	419.13	1.307	418.1	1.33
8	90.49	0	0.85	391.72	1.2329	390.71	1.22



VII. CONCLUSION

As a result of the present work following conclusion can be made.

- 1) Generator has highest contribution in entropy generation of the system hence optimizing generator parameter with a view of reducing entropy is thermodynamically more important.
- 2) Using ANN we have predict the entropy values and refine that values at minimum entropy level for stability of system.

- 3) As from the analysis actual and predicted values small difference. So we can predict any level entropy for different inputs parameters.

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